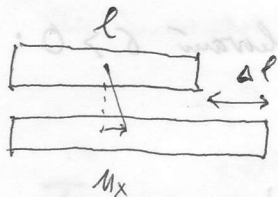


Prințipul deplasării la loc

• Tensor deformației

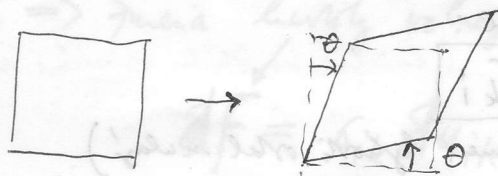
Avem $\vec{r} \rightarrow \vec{r} + \vec{u}(\vec{r})$



$$u_x = \frac{\Delta l}{l} \cdot x = u_{xx} \cdot x$$

$$u_{xx} = \frac{\partial u_x}{\partial x}$$

întindere deformație:



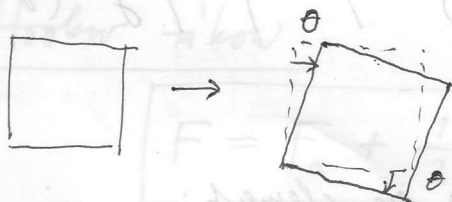
$$u_x = \theta y$$

$$u_y = \theta x$$

$$u_{xy} = \frac{\partial u_x}{\partial y} = \theta$$

$$u_{yx} = \frac{\partial u_y}{\partial x} = \theta$$

ale:



$$u_x = \theta y$$

$$u_y = -\theta x$$

$$u_{xy} = -u_{yx}$$

cîrca rotație

⇒ definiție

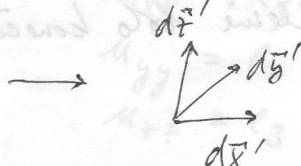
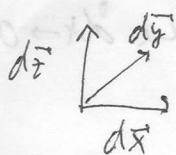
$$u_{ij} = \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right)$$

$$u_{ij} = u_{ji}$$

$$u_{ij} = 0$$

pe cîrca rotație

zucăra obiectu pî deformației:



$$dV = dx dy dz$$

$$dV' = d\vec{x}' \cdot (d\vec{y}' \times d\vec{z}')$$

$$\frac{dV'}{dV} = \epsilon_{\alpha\beta\gamma} (\delta_{\alpha x} + \partial_x u_\alpha) (\delta_{\beta y} + \partial_y u_\beta) (\delta_{\gamma z} + \partial_z u_\gamma)$$

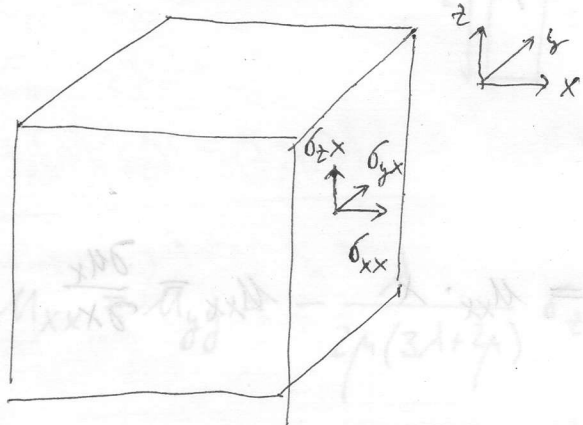
$$\frac{dV'}{dV} = 1 + \vec{\nabla} \cdot \vec{u} + \underbrace{\left(\frac{\partial u_y}{\partial z} \frac{\partial u_z}{\partial y} - \frac{\partial u_z}{\partial y} \frac{\partial u_y}{\partial z} \right) + \left(\frac{\partial u_z}{\partial x} \frac{\partial u_x}{\partial z} - \frac{\partial u_x}{\partial z} \frac{\partial u_z}{\partial x} \right)}_{\text{cîrca rotație}}$$

$$V' = V + \delta V \rightarrow \frac{\delta V}{V} = \vec{\nabla} \cdot \vec{u}$$

$$+ \left(\frac{\partial u_x}{\partial x} \frac{\partial u_y}{\partial y} - \frac{\partial u_y}{\partial x} \frac{\partial u_x}{\partial y} \right) + O(u^3)$$

• Tensor napätia

$$\int f_i dV = \int \frac{\partial \sigma_{ik}}{\partial x_k} dV = \oint \sigma_{ik} dS_k$$



↓
 rila, ktorou pôsobí skutoč
 elementu na element dV ;
 pri natáhaní $\sigma > 0$:



$$f dx = \sigma(x+dx) - \sigma(x)$$

Polybová rovnica:

$$\rho \ddot{u}_i = \frac{\partial \sigma_{ik}}{\partial x_k} + f_i$$

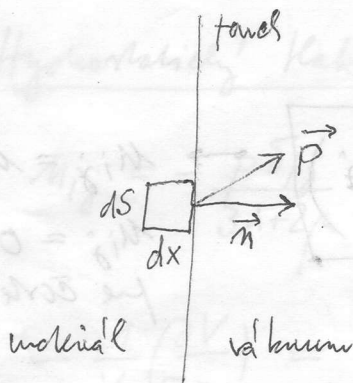
Príklad:

$$\sigma_{ik} = \sigma_{ki}$$

(ak moment hybnosti ostal nulový)

objemová rila, napr $\vec{F} = \rho \vec{g}$ (gravitácia)

Okrajová podmienka:



rila pôsobiaci na element:

$$P_i dS - \sigma_{ik} dS_k = \rho \ddot{u}_i dS dx$$

$$dS_k = n_k dS \quad \vec{n}_k = \text{normála k ploche}$$

$$\rho \ddot{u}_i = \frac{P_i - \sigma_{ik} n_k}{dx}$$

Ak zjednodušíme toto konečne pre $dx \rightarrow 0$:

$$P_i = \sigma_{ik} n_k$$

vonkajší tlak; $P < 0$ je stlačenie

príklad: hydrostatický tlak: $\sigma_{ik} = -p \delta_{ik} \quad p > 0$

Termodynamika deformácie

systém konš. fr. ču
(pri infiničnej deformácii $\delta u(\vec{r})$)

$$\begin{aligned} \int dV f_i \delta u_i &= \int dV \partial_k \sigma_{ik} \delta u_i \\ &= \underbrace{\int dV \partial_k (\sigma_{ik} \delta u_i)}_{=0 \text{ lebo } \delta \vec{u}=0 \text{ v nekonečne}} - \underbrace{\int dV \sigma_{ik} \partial_k \delta u_i}_{= \int dV \sigma_{ik} \delta u_{ik}} \end{aligned}$$

Teda systém konš. fr. ču $\rightarrow \int dV \sigma_{ik} \delta u_{ik} \xrightarrow{\text{analog}} p dV$

$\Rightarrow$ zmena ľubovoľnej energie

$$dF = \sigma_{ik} du_{ik} - S dT \rightarrow$$

$$\sigma_{ik} = \left(\frac{\partial F}{\partial u_{ik}} \right)_T$$

Hookeov zákon

$$F = F(T, u_{ik})$$

$$F = F_0 + \frac{1}{2} C_{ijkl} u_{ij} u_{kl}$$

ij -- 6 hodnot: $xx, yy, zz, xy, yz, zx \leftrightarrow 1, 2, 3, 4, 5, 6$

C_{ijkl} -- $6 \times 6 = 36$ komponent

$C_{ijke} = C_{keij} \rightarrow 6 + 5 + 4 + 3 + 2 + 1 = 21$ komponent

definujeme

$$\begin{aligned} u_{xx} &= \epsilon_1 & 2u_{yz} &= \epsilon_4 \\ u_{yy} &= \epsilon_2 & 2u_{zx} &= \epsilon_5 \\ u_{zz} &= \epsilon_3 & 2u_{xy} &= \epsilon_6 \end{aligned}$$

$$F = F_0 + \frac{1}{2} C_{\alpha\beta} \epsilon_\alpha \epsilon_\beta$$

Počet nesúvislých komponent $C_{\alpha\beta}$ je dikovaný symetriou systému

$$\text{Hooke: } \sigma_{ij} = \left(\frac{\partial F}{\partial u_{ij}} \right)_T \rightarrow$$

$$\sigma_{ij} = C_{ijkl} u_{kl}$$

faktor 2 m' OK,
lebo
 $C_{ijke} (u_{kl} + u_{lk})$
faktor 2 pre $k \neq l$.

$$\begin{aligned} \epsilon_1 &= \epsilon_{xx}, \epsilon_2 = \epsilon_{yy}, \epsilon_3 = \epsilon_{zz} \\ \epsilon_4 &= \epsilon_{yz}, \epsilon_5 = \epsilon_{zx}, \epsilon_6 = \epsilon_{xy} \end{aligned}$$

$$\sigma_\alpha = C_{\alpha\beta} \epsilon_\beta$$

• Priklad: kubický systém

$$\left. \begin{aligned} C_{11} &= C_{22} = C_{33} \\ C_{44} &= C_{55} = C_{66} \\ C_{12} &= C_{23} = C_{31} \end{aligned} \right\} 3 \text{ nezávislé konstanty}$$

$$C_{14} = \dots = 0$$

$$C_{xxyz} = 0$$

Například, při změně $y \rightarrow -y$
nezmění se ušetření, ale

$$u_{yz} \rightarrow -u_{yz}$$

$$u_{xx} \rightarrow u_{xx}$$

Tedy

$$C_{14} u_{xx} u_{yz} = -C_{14} u_{xx} u_{yz}$$

(energie křivky by musela být rovná 0)

$$\rightarrow C_{14} = 0$$

$$C_{\alpha\beta} = \begin{pmatrix} C_{11} & C_{12} & C_{12} & 0 & 0 & 0 \\ C_{12} & C_{11} & C_{12} & 0 & 0 & 0 \\ C_{12} & C_{12} & C_{11} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{44} & 0 \\ 0 & 0 & 0 & 0 & 0 & C_{44} \end{pmatrix}$$

$$F = F_0 + \frac{1}{2} C_{11} (u_{xx}^2 + u_{yy}^2 + u_{zz}^2) + C_{12} (u_{xx} u_{yy} + u_{yy} u_{zz} + u_{zz} u_{xx})$$

$$+ 2 C_{44} (u_{xy}^2 + u_{yz}^2 + u_{zx}^2) \quad \dots \text{např. } 2 u_{xy}^2 = \frac{1}{2} (u_{xy}^2 + u_{yx}^2 + 2 u_{xy} u_{yx})$$

alebo

$$F = F_0 + \frac{1}{2} C_{11} (\epsilon_1^2 + \epsilon_2^2 + \epsilon_3^2) + C_{12} (\epsilon_1 \epsilon_2 + \epsilon_2 \epsilon_3 + \epsilon_3 \epsilon_1) + \frac{1}{2} C_{44} (\epsilon_4^2 + \epsilon_5^2 + \epsilon_6^2)$$

→ Hook:

$$\begin{aligned} \sigma_{xx} &= C_{11} u_{xx} + C_{12} (u_{yy} + u_{zz}) \\ \sigma_{xy} &= 2 C_{44} u_{xy} \end{aligned}$$

a cyklické změny

Até vily n' celkové $\rightarrow C_{12} = C_{44}$ Cauchy

v GPa

	C_{11}	C_{44}	C_{12}	
Si	165	80	64	křivá lehká vřtba
Na	7.6	4.3	6.3	} korová vřtba
Aw	790	42	161	
(6K) Ne	1.6	0.93	0.85	van der Waals $\approx$ Cauchy
Fe	230	117	135	korová vřtba
(diamant) C	1040	550	170	křivá lehká vřtba
NaCl	49	13	13	ionový krystal $\approx$ Cauchy

Príklad 2: izotropný systém $\rightarrow$ polykrystal, sklo, guma, ... 5

Formulu pre kvadratickú hustotu možno písať:

$$F = F_0 + C_{44} u_{ij} u_{ij} + \frac{1}{2} C_{12} (u_{xx} + u_{yy} + u_{zz})^2 + \frac{1}{2} (C_{11} - C_{12} - 2C_{44}) (u_{xx}^2 + u_{yy}^2 + u_{zz}^2)$$

nie je rotačne invariantná

$\rightarrow$ náhodane $C_{11} = C_{12} + 2C_{44}$

$$\left. \begin{array}{l} C_{44} = \mu \\ C_{12} = \lambda \end{array} \right\} \text{Lamé}$$

$$F = F_0 + \frac{\lambda}{2} u_{ii}^2 + \mu u_{ij} u_{ij}$$

Hook:

$$\sigma_{ij} = \lambda \delta_{ij} \bar{\nu} \cdot \bar{u} + 2\mu u_{ij}$$

$\downarrow$

$$\sigma_{ii} = (3\lambda + 2\mu) u_{ii}$$

$\downarrow$

$$u_{ij} = \frac{1}{2\mu} \sigma_{ij} - \frac{\lambda \delta_{ij}}{2\mu(3\lambda + 2\mu)} \sigma_{ll}$$

možno aj písať

$$F = F_0 + \frac{1}{2} \left(\lambda + \frac{2\mu}{3} \right) (u_{ii})^2 + \mu \left(u_{ij} - \frac{1}{3} \delta_{ij} u_{ll} \right) \left(u_{ij} - \frac{1}{3} \delta_{ij} u_{ll} \right)$$

stopa
tenzora

hvestičkové reči

tenzor so stopou = 0

stabilita $\rightarrow$
$$\left\{ \begin{array}{l} K = \lambda + \frac{2\mu}{3} > 0 \\ \mu > 0 \end{array} \right.$$

polykrová rovnica

$$\rho \ddot{u}_i = \frac{\partial \sigma_{ij}}{\partial x_j} \rightarrow$$

$$\rho \ddot{\vec{u}} = (1 + \mu) \bar{\nu} (\bar{\nu} \cdot \vec{u}) + \mu \Delta \vec{u}$$

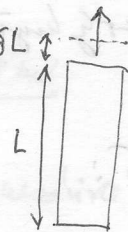
podľa týchto

$$v_{II} = \sqrt{\frac{\lambda + 2\mu}{\rho}}$$

príčný

$$v_I = \sqrt{\frac{\mu}{\rho}}$$

• Homogénne natiahnutie: $\delta L \uparrow$, $\sigma_{zz} \neq 0$, ostatní $\sigma_{ij} = 0$



$$\sigma_{zz} = E \epsilon_{zz} = E \frac{\delta L}{L}$$

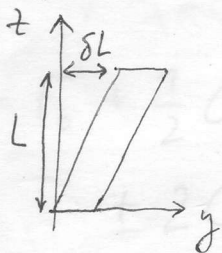
$$E = \frac{\mu(3\lambda + 2\mu)}{\lambda + \mu} \quad \text{Youngov modul pružnosti}$$

$$\epsilon_{xx} = \epsilon_{yy} = -\frac{\lambda}{2\mu(3\lambda + 2\mu)} \sigma_{zz}$$

$$-\frac{\epsilon_{xx}}{\epsilon_{zz}} = \frac{\lambda}{2(\lambda + \mu)} \equiv \nu \quad \text{Poisson}$$

$$\text{termodynamika: } -1 < \nu < \frac{1}{2}$$

• Homogénna šikmá deformácia



iba $\sigma_{yz} \neq 0$

$$\sigma_{yz} = 2\mu \epsilon_{yz} = \mu \frac{\partial u_y}{\partial z}$$

$$\sigma_{yz} = \mu \frac{\delta L}{L}$$

šikmý modul

• Hydrostatický tlak

$$\sigma_{ij} = -p \delta_{ij}$$

$$\epsilon_{ij} = -\frac{p \delta_{ij}}{3\lambda + 2\mu}$$

$$\vec{\nabla} \cdot \vec{u} = -\frac{3p}{3\lambda + 2\mu} \rightarrow \frac{\delta V}{V} = \vec{\nabla} \cdot \vec{u}$$

$$-\frac{1}{V} \left(\frac{\partial V}{\partial p} \right)_T = \frac{1}{K}, \quad \text{kde } K = \lambda + \frac{2}{3}\mu \quad \text{modul objemový, Mači klavír}$$

moduly i šikmých a ľalok

	E (GPa)	ν
guma	0,0005	0.5
liate slovo	5	0.5
sklo	55	0.16
liate železo	110	0.3
ocel	200	0.3
wolfrám	400	0.3

väčšina materiálov: $\nu > 0$

anizotropné materiály: $\nu < 0$

elast. konstanty: energia / objem

$$\text{typické čísla: } \frac{1 \text{ eV}}{10^{-30} \text{ m}^3} \sim 10^{11} \frac{\text{N}}{\text{m}^2} \sim 10^2 \text{ GPa}$$

guma: ima' energetická štruktúra!